## DA1.4F <br> Floating Spring Return Actuator

## Application

The JOVENTA SPRING RETURN electric
damper-actuator series, has been specially developed for the motorized operation of safety air dampers (anti-icing) in air conditioning systems, smoke evacuation dampers and sealing dampers. When the control signal is applied the actuator drives the damper to the operational position, while evenly tensioning the integrated spring. After a power failure the stored energy in the spring immediately brings the damper to the safety position.
Manual operation is automatically cancelled when the actuator is in electrical operation.
The compact design and universal adapter fitted with limitation of rotation angle make this actuator highly versatile.

## Features

- 3-point control
- Up to 5 actuators in parallel operation possible
- Plug-in terminal block connection
- Simple direct mounting with universal adapter on $\varnothing 10 \mathrm{~mm}$ to 20 mm shaft or 10 mm to 16 mm square shaft
77 mm min shaft length
- Selectable direction of rotation
- Limitation of rotation angle
- Manual positioning with crank handle
- 2 adjustable auxiliary switches (See back page for settings)
- Automatic shut-off at end position (overload switch)
- Feedback potentiometer
- Energy saving at end positions
- Actuators available with 1 m halogen-free cable
- Customized versions available
- Devices meet CE requirements


## Accessories

- ZK Damper linkage selection
- ZKG Ball joints (see data sheet 6.10)

Ordering Codes


Technical Specifications

| Actuator | DAF1.4F(S)(Px) |
| :---: | :---: |
| Torque | 16 Nm |
| Damper area* | $3.0 \mathrm{~m}^{2}$ |
| Running Time Motor | $90 . .120 \mathrm{~s}$ |
| Running Time Spring Return | 10 s |
| Supply Voltage | AC/DC 24 V |
| Frequency | $50-60 \mathrm{~Hz}$ |
| Power Consumption <br> - Running <br> - At end position | $\begin{gathered} \text { 10.0 W } \\ 4.0 \mathrm{~W} \end{gathered}$ |
| Dimensioning | 18.0 VA / 4 A @ 2 ms |
| Control Signal | 3-Point Floating |
| Position Signal | Potentiometer |
| Angle of rotation/Working range | $90^{\circ}$ (93 ${ }^{\circ} \mathrm{mech}$.) |
| Angle of rotation/Limitation | $0^{\circ} \ldots 30^{\circ}$ and $90 \ldots 60^{\circ}$ |
| Auxiliary Switches <br> - Setting range | $3(1.5) \mathrm{A}, \mathrm{AC} 230 \mathrm{~V}$ <br> $5^{\circ} . . .85^{\circ}$ < adjustable |
| Potentiometer load | 0.5 W |
| Tolerance | $\pm 10 \%$ |
| Cable aperture connection | PG11 |
| Life time | 60.000 rotations |
| Noise level | 50 dB (A) |
| Protection Class | 11 |
| Degree of Protection | IP 54 |
| Mode of Action | Type 1 |
| Ambient conditions <br> - Operating temperature <br> - Storage temperature <br> - Humidity | $\begin{aligned} & -20 \ldots+50^{\circ} \mathrm{C} / \text { IEC } 721-3-3 \\ & -30 \ldots+60^{\circ} \mathrm{C} / \text { IEC } 721-3-2 \\ & 5 . . .95 \% \text { r.F. no condensed } \end{aligned}$ |
| Weight | 2.7 Kg |
| Service | Maintenance-free |
| Standards <br> - Mechanics <br> - Electronics <br> - EMC Emissions <br> - EMC Immunity | EN 60529 / EN 60 730-2-14 EN 60 730-2-14 EN 50 081-1:92 / IEC 61000-6-3:96 EN 50 082-2:95 / IEC 61000-6-2:99 |

[^0]
## DA1.4F <br> Floating Spring Return Actuator

## Wiring Diagram

$$
\perp \sim A C 24 V \pm 20 \%
$$

$$
-\quad+\mathrm{DC} 24 \mathrm{~V} \pm 10 \%
$$

When changing the directions of rotations several times in quick succession, allow a delay of 1 sec . after each change.

Parallel Connections


Auxiliary Switches (S)


Potentiometer


P1 $=1 \mathrm{~K} \Omega / 0,5 \mathrm{~W} \pm 10 \%$ P2 $=140 \mathrm{~K} \Omega / 0,5 \mathrm{~W} \pm 10 \%$

## Dimensions in mm



Changing the direction of rotation
The change in rotation direction is archieved by removing the adapter bush from one side and replacing it on the other side.


Factory setting:
Clockwise rotation.


Setting the auxiliary switches
Factory setting
Switch a at $10^{\circ}$
Switch b at $80^{\circ}$
The switching position can be manually changed to any required position by turning the ratchet


## Limitation of rotation Angle

The limitation or rotation/working range can, through segments 1 and 2 , be reduced by up to $30^{\circ}$ from both end positions.



[^0]:    *Caution: Please note damper manufacturer's information concerning the open/close torque

