## Application

The JOVENTA electric, Spring Return damperactuator series has been specially developed for the motorized operation of safety air dampers (anti-icing) in air conditioning systems, smoke evacuation dampers and sealing dampers. When the control signal is applied the actuator drives the damper to the operational position, while evenly tensioning the integrated spring. After a power failure the stored energy in the spring immediately brings the damper to the safety position.
Manual operation is automatically cancelled when the actuator is in electrical operation.
The compact design and universal adapter fitted with limitation of rotation angle make this actuator highly versatile.

## Features

- DC $0 . . .10 \mathrm{~V}$ or $0 . . .20 \mathrm{~mA}$ control
- Load independent running time
- Up to 5 actuators in parallel operation possible
- Plug-in terminal block connection
- Simple direct mounting with universal adapter on $\varnothing 10 \mathrm{~mm}$ to 20 mm shaft or 10 mm to 16 mm square shaft 77 mm min shaft length
- Selectable direction of rotation
- Limitation of rotation angle
- Manual positioning with crank handle
- 2 adjustable auxiliary switches (See back page for settings)
- Automatic shut-off at end position (overload switch)
- Energy saving at end positions
- Actuators available with 1 m halogen-free cable
- Customized versions available
- Devices meet CE requirements


## Accessories

- ZK damper linkage selection
- ZKG ball joints
(see data sheet 6.10)

Ordering Codes

| Codes | Descriptions |
| :--- | :--- |
| DM1.1F | AC/DC 24 V |
| DM1.1FS | AC/DC 24 V , with 2 auxiliary switches |



Technical Specifications

| Actuator | DM1.1F(S) |
| :---: | :---: |
| Torque | 16 Nm |
| Damper area* | $3.0 \mathrm{~m}^{2}$ |
| Running Time Motor | 90 s |
| Running Time Spring Return | 10 s |
| Supply Voltage | AC/DC 24 V |
| Frequency | $50-60 \mathrm{~Hz}$ |
| Power Consumption <br> - Running <br> - At end position | $\begin{aligned} & \text { 7.0 W } \\ & 0.6 \mathrm{~W} \end{aligned}$ |
| Dimensioning | 12.0 VA / 6 A @ 2 ms |
| Control Signal $\begin{array}{r} -Y 1 \\ -Y 2 \end{array}$ | $\begin{gathered} \text { DC } 0 . . .10 \mathrm{~V} \\ 0 \ldots . .20 \mathrm{~mA} \end{gathered}$ |
| Position Signal | DC $0 . . .10 \mathrm{~V}$ |
| Angle of rotation/Working range | $90^{\circ}$ (93 ${ }^{\circ} \mathrm{mech}$.) |
| Angle of rotation/Limitation | $0^{\circ} \ldots 30^{\circ}$ and $90^{\circ} \ldots 60^{\circ}$ |
| Auxiliary Switches <br> - Setting range | $\begin{gathered} 3(1.5) \mathrm{A}, \mathrm{AC} 230 \mathrm{~V} \\ 5^{\circ} \ldots 85^{\circ} \end{gathered}$ |
| Life time | 60.000 rotations |
| Noise level | $50 \mathrm{~dB}(\mathrm{~A})$ |
| Protection Class | 11 |
| Degree of Protection | IP 54 |
| Cable aperture connections | PG11 |
| Mode of Action | Type 1 |
| Ambient conditions <br> - Operating temperature <br> - Storage temperature <br> - Humidity | $\begin{aligned} & -20 \ldots+50^{\circ} \mathrm{C} / \text { IEC } 721-3-3 \\ & -30 \ldots+60^{\circ} \mathrm{C} / \text { IEC } 721-3-2 \\ & 5 . . .95 \% \text { r.F. no condensed } \end{aligned}$ |
| Weight | 2.7 Kg |
| Service | Maintenance-free |
| Standards <br> - Mechanics <br> - Electronics <br> - EMC Emissions <br> - EMC Immunity | EN 60529 / EN 60 730-2-14 EN 60 730-2-14 EN 50 081-1:92 / IEC 61000-6-3:96 EN 50 082-2:95 / IEC 61000-6-2:99 |

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## Wiring Diagram



Parallel Connections


## Position trasmitter



The actuator can also be controlled using the Johnson Positioner (PA-PF) with Control signal of DC $0 . . .10 \mathrm{~V}$. For further information concerning the PA and PF Positioner please refer to data sheet 6.20.


## Control Signal: Factory setting

| Control signal Y1 | DC 0...10V | Microswitch d1 |  |
| :---: | :---: | :---: | :---: |
| Input Resistance | $\mathrm{Ri}=200 \mathrm{k} \Omega$ | Self-adapting | Self-adapting |
| Control signal Y2 | 0... 20 mA | OFF | ON |
| Input Resistance | $\mathrm{Ri}=388 \Omega$ | $\mathrm{ON}^{\mathrm{ON}}$ | ON |
| Position signal U1 | DC $0 . .10 \mathrm{~V}$ |  |  |
| Load resistance | $\mathrm{R} \geq 10 \mathrm{k} \Omega$ | 12 | 12 |

The self-adapting mode is activated by switching the micro-switch d 1 to ON . In this mode the running time, control signals Y 1 and Y 2 and the output signal U will set to match the mechanically selected range of rotation.
The minimum working range that can be adapted to is $30^{\circ}$.
During the self-adapting procedure the actuator finds and stores both end positions.
Even after a power failure the stored values can be recalled.
If the angle of rotation is changed the actuator will automatically match the new working range.

## Changing the control setting

The potentiometers O and S help to match control signals Y 1 and Y 2 to any make of controller.

Example 1
Control signal Y1 working between DC $2 \ldots 10 \mathrm{~V}$
Setting: Starting point $\quad \mathrm{O}=2$
working range $\quad \mathrm{S}=8$

Example 2
Control signal Y2 working between 6 ... 18 mA
Setting: Starting point $\quad \mathrm{O}=3$

Start point O


| Scale O | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| for $\mathrm{Y} 1(\mathrm{VDC})$ | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| for $\mathrm{Y} 2(\mathrm{~mA})$ | 0 | 2 | 4 | 6 | 8 | 10 | 12 | 14 | 16 |

Working range $S$

|  | Scale S | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | for Y1 (VDC) | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
|  | for Y2 (mA) | 4 | 6 | 8 | 10 | 12 | 14 | 16 | 18 | 20 |

Setting the auxiliary switches
Factory setting
Switch a at $10^{\circ}$
Switch b at $80^{\circ}$
The switching position can be manually changed to any required position by turning the ratchet


## Limitation of rotation angle

The $90^{\circ}$ angle of rotation/working range can, through segments 1 and 2 , be reduced by up to $30^{\circ}$ from both end positions.

Segment 1
Segment 2



[^0]:    *Caution: Please note damper manufacturer's information concerning the open/close torque.

